

Simulation Based on Michel Fodje's epr-simple simulation translated from Python to Mathematica by John Reed 13 Nov 2013 and Quaternions Modified by Fred Diether for Completely Local-Realistic Sep 2021 Some parts by Bill Nelson. Includes Joy's S^3 Quaternion Model.

Load Quaternion Package, Set Run Time Parameters, Initialize Arrays and Tables

```
In[632]:= << Quaternions` ;
β0 = Quaternion[1, 0, 0, 0];
β1 = Quaternion[0, 1, 0, 0];
β2 = Quaternion[0, 0, 1, 0];
β3 = Quaternion[0, 0, 0, 1];
Qcoordinates = {β1, β2, β3};
m = 200000;
trialDeg = 721;
Ls1 = ConstantArray[0, m];
Ls2 = ConstantArray[0, m];
λ1 = ConstantArray[0, m];
λ2 = ConstantArray[0, m];
outAa = Table[{0, 0, 0, 0, 0, 0, 0}, m];
outBb = Table[{0, 0, 0, 0, 0, 0, 0}, m];
plotq = Table[{0, 0}, m];
a1 = ConstantArray[0, m];
b1 = ConstantArray[0, m];
A = ConstantArray[0, m];
B = ConstantArray[0, m];
nPP = ConstantArray[0, trialDeg];
nNN = ConstantArray[0, trialDeg];
nPN = ConstantArray[0, trialDeg];
nNP = ConstantArray[0, trialDeg];
nAP = ConstantArray[0, trialDeg];
nBP = ConstantArray[0, trialDeg];
nAN = ConstantArray[0, trialDeg];
nBN = ConstantArray[0, trialDeg];
φ = 3.1; β = 0.32; ξ = - $\frac{4\pi}{45}$ ; (*Adjustable parameters for fine tuning*)
```

Generating Particle Data with Three Independent Do-Loops

```
In[660]:= Do[θ = RandomReal[{-179, 180}]; (*Singlet vector angle*) (*Hidden Variable*)
λ1[[i]] = β (Cos[ $\frac{\theta}{\phi}$ ] ^ 2);
λ2[[i]] = Sign[θ];
θθ = N[Flatten[{FromPolarCoordinates[{1, θ * π/180}], 0}]];
Ls1[[i]] = λ2[[i]] * θθ.Qcoordinates;
Ls2[[i]] = -Ls1[[i]], {i, m}]
```

```
In[661]:= Do[a = RandomInteger[{-179, 180}]; (*Detector vector angle 1 degree increments*)
  aa = N[Flatten[{FromPolarCoordinates[{1, a *  $\pi$ /180}], 0}]];
  Da = aa.Qcoordinates; (*Convert to quaternion coordinates*)
  qa = Da ** Ls1[[i]];
  aq = -(Ls1[[i]] ** Da);
  If[Abs[Re[qa]] <  $\lambda$ 1[[i]], C1 = f1, C1 = g1];
  If[Abs[Re[qa]] >  $\lambda$ 1[[i]],
    Aa = Re[Da ** Limit[Ls1[[i]], Ls1[[i]] -> Sign[Re[Da ** Ls1[[i]]]] Da]],
    Aa =  $\lambda$ 2[[i]] * Sign[qa[[4]] +  $\xi$ ]];
  A5 =  $\lambda$ 2[[i]] * Sign[qa[[4]] +  $\xi$ ]];
  outAa[[i]] = {a, Aa, i, C1, A5, qa, aq}, {i, m}]
outA1 = Select[outAa, MemberQ[#, g1] &]; (*Split outAa into outA1 and outA2*)
outA2 = Select[outAa, MemberQ[#, f1] &];
```

```
In[663]:= Do[b = RandomInteger[{-179, 180}]; (*Detector vector angle 1 degree increments*)
  bb = N[Flatten[{FromPolarCoordinates[{1, b *  $\pi$ /180}], 0}]];
  Db = bb.Qcoordinates; (*Convert to quaternion coordinates*)
  qb = Ls2[[i]] ** Db;
  bq = -(Db ** Ls2[[i]]);
  If[Abs[Re[qb]] <  $\lambda$ 1[[i]], C2 = f2, C2 = g2];
  If[Abs[Re[qb]] >  $\lambda$ 1[[i]],
    B = Re[Db ** Limit[Ls2[[i]], Ls2[[i]] -> Sign[Re[Db ** Ls2[[i]]]] Db]],
    B = - $\lambda$ 2[[i]] * Sign[qb[[4]] +  $\xi$ ]];
  B5 = - $\lambda$ 2[[i]] * Sign[qb[[4]] +  $\xi$ ]];
  outBb[[i]] = {b, B, i, C2, B5, qb, bq}, {i, m}]
outB1 = Select[outBb, MemberQ[#, g2] &]; (*Split outBb into outB1 and outB2*)
outB2 = Select[outBb, MemberQ[#, f2] &];
```

Matching Events Observed by Alice and Bob using Trial Numbers

```
In[665]:= list13 = outA1[[All, 3]]; (*Two lists of only trial numbers used for matching*)
list23 = outB1[[All, 3]];
```

Local Detection Analysis of the Events Observed by Alice

```
In[667]:= listA4 = Select[outA1, Intersection[#[[3]], list23] == {#[[3]]} &];
(*Events in outA1 that match go to listA4*)
listad3 = listA4[[All, 3]];
listA3 = Select[outA1, Intersection[#[[3]], listad3] != {#[[3]]} &];
(*Events in outA1 that do not match go to listA3*)
```

```
In[670]:= M = Length[listA3];
listA6 = Table[{0, 0, 0, 0, 0, 0, 0}, M]; (*Quaternion sign change*)
qaaq = ConstantArray[0, M];
listA36 = listA3[[All, 6]];
listA37 = listA3[[All, 7]];
Do[If[listA3[[i]][[2]] == listA3[[i]][[5]],
  qaaq[[i]] = 1, qaaq[[i]] = Re[listA36[[i]] ** listA37[[i]]]];
listA6[[i]] = {listA3[[i]][[1]], qaaq[[i]] * listA3[[i]][[2]], listA3[[i]][[3]],
  listA3[[i]][[4]], listA3[[i]][[5]], listA3[[i]][[6]], listA3[[i]][[7]]}, {i, M}]
```

```
In[676]:= outA = Sort[Catenate[{listA4, outA2, listA6}], #1[[3]] < #2[[3]] &];
(*Combine lists and sort*)
a1 = outA[[All, 1]];
A = outA[[All, 2]]; (*These results are what Alice observes as defined in Eq.(13)*)
```

Local Detection Analysis of the Events Observed by Bob

```

In[679]:= listB4 = Select[outB1, Intersection[#[[3]], list13] == {#[[3]]} &];
(*Events in outB1 that match go to listB4*)
listbd3 = listB4[[All, 3]];
listB3 = Select[outB1, Intersection[#[[3]], listbd3] != {#[[3]]} &];
(*Events in outB1 that do not match go to listB3*)

In[682]:= M2 = Length[listB3];
listB6 = Table[{0, 0, 0, 0, 0, 0, 0}, M2]; (*Quaternion sign change*)
qbbq = ConstantArray[0, M2];
listB36 = listB3[[All, 6]];
listB37 = listB3[[All, 7]];
Do[If[listB3[[i]][[2]] == listB3[[i]][[5]],
  qbbq[[i]] = 1, qbbq[[i]] = Re[listB36[[i]] ** listB37[[i]]];
  listB6[[i]] = {listB3[[i]][[1]], qbbq[[i]] * listB3[[i]][[2]], listB3[[i]][[3]],
    listB3[[i]][[4]], listB3[[i]][[5]], listB3[[i]][[6]], listB3[[i]][[7]]}, {i, M2}]

In[688]:= outB = Sort[Catenate[{listB4, outB2, listB6}], #1[[3]] < #2[[3]] &];
(*Combine lists and sort*)
b1 = outB[[All, 1]];
B = outB[[All, 2]]; (*These results are what Bob observes as defined in Eq.(20)*)

```

Statistical Analysis of the Particle Data Received from Alice and Bob

```

In[691]:= theta = ConstantArray[0, m];
Do[ $\theta_1 = a_1[[j]] - b_1[[j]] + 361$ ;
  (*All angles are shifted by 361 degrees since  $\theta_1$  is an index*)
  theta[[j]] =  $\theta_1$ ;
  aliceD = A[[j]]; bobD = B[[j]];
  If[aliceD == 1, nAP[[ $\theta_1$ ]] ++];
  If[bobD == 1, nBP[[ $\theta_1$ ]] ++];
  If[aliceD == -1, nAN[[ $\theta_1$ ]] ++];
  If[bobD == -1, nBN[[ $\theta_1$ ]] ++];
  If[aliceD == 1 && bobD == 1, nPP[[ $\theta_1$ ]] ++];
  If[aliceD == 1 && bobD == -1, nPN[[ $\theta_1$ ]] ++];
  If[aliceD == -1 && bobD == 1, nNP[[ $\theta_1$ ]] ++];
  If[aliceD == -1 && bobD == -1, nNN[[ $\theta_1$ ]] ++], {j, m}]

```

Calculating Mean Values of A, B, and AB, and Plotting the Results

```

In[693]:= pPP = 0; pPN = 0; pNP = 0; pNN = 0;
mean = ConstantArray[0, trialDeg];
Do[sum = nPP[[i]] + nPN[[i]] + nNP[[i]] + nNN[[i]];
  If[sum == 0, Goto[jump],
    {pPP = nPP[[i]] / sum;
     pNP = nNP[[i]] / sum;
     pPN = nPN[[i]] / sum;
     pNN = nNN[[i]] / sum;
    mean[[i]] = pPP + pNN - pPN - pNP};
  Label[jump], {i, trialDeg}]

```

```

In[696]:= simulation = ListPlot[mean, PlotMarkers → {Automatic, Tiny}];
negcos = Plot[-Cos[x Degree], {x, 0, 720}, PlotStyle → {Magenta}, AspectRatio → 7/16,
  Ticks → {{0, -360°}, {90, -270°}, {180, -180°}, {270, -90°}, {360, 0°}, {450, 90°},
    {540, 180°}, {630, 270°}, {720, 360°}}, Automatic, GridLines → Automatic];
p1 = Plot[-1 + 2 x Degree / π, {x, 0, 180}, PlotStyle → {Gray, Dashed}];
p2 = Plot[3 - 2 x Degree / π, {x, 180, 360}, PlotStyle → {Gray, Dashed}];
p3 = Plot[-5 + 2 x Degree / π, {x, 360, 540}, PlotStyle → {Gray, Dashed}];
p4 = Plot[7 - 2 x Degree / π, {x, 540, 720}, PlotStyle → {Gray, Dashed}];

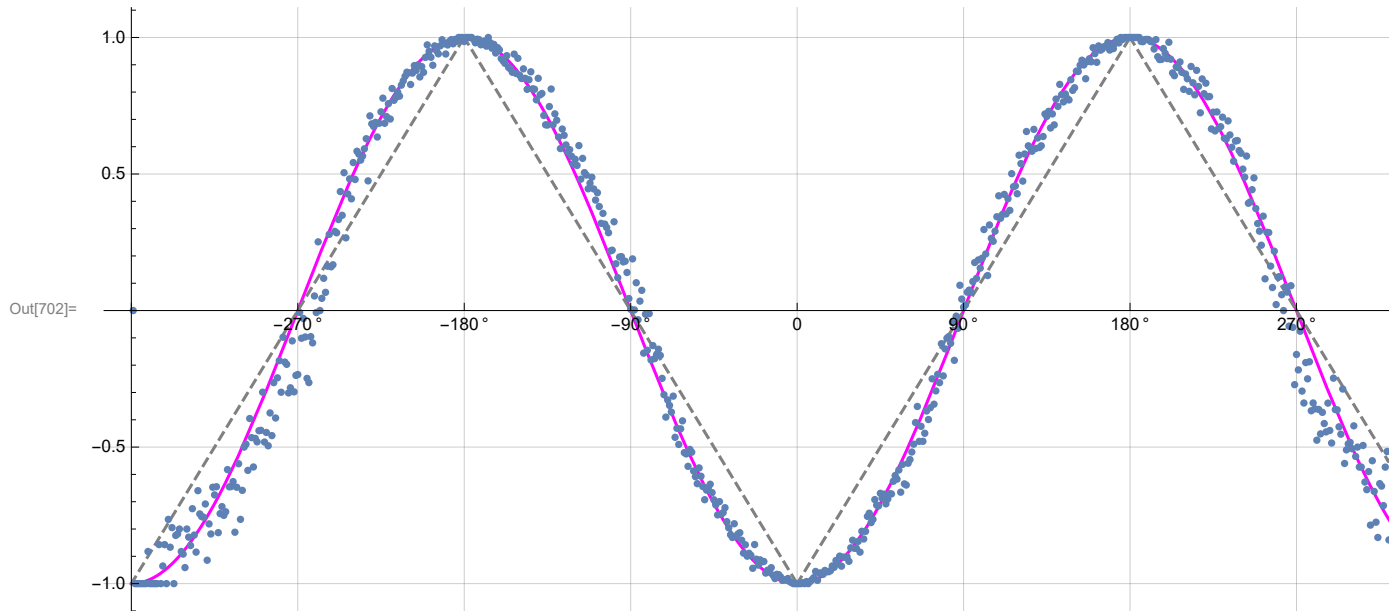
```

Comparing Mean Values with -Cosine Function and Computing Averages

```

In[702]:= Show[negcos, p1, p2, p3, p4, simulation]

```



```

In[703]:= AveA = N[Sum[A[[i]], {i, m}]/m];
AveB = N[Sum[B[[i]], {i, m}]/m];
Print["AveA = ", AveA]
Print["AveB = ", AveB]
PAP = N[Sum[nAP[[i]], {i, trialDeg}]];
PBP = N[Sum[nBP[[i]], {i, trialDeg}]];
PAN = N[Sum[nAN[[i]], {i, trialDeg}]];
PBN = N[Sum[nBN[[i]], {i, trialDeg}]];
PA1 = PAP / (PAP + PAN);
PB1 = PBP / (PBP + PBN);
Print["P(A+) = ", PA1]
Print["P(B+) = ", PB1]
totAB = Sum[nPP[[i]] + nNN[[i]] + nPN[[i]] + nNP[[i]], {i, trialDeg}]
PP = N[Sum[nPP[[i]], {i, trialDeg}]/totAB]
NN = N[Sum[nNN[[i]], {i, trialDeg}]/totAB]
PN = N[Sum[nPN[[i]], {i, trialDeg}]/totAB]
NP = N[Sum[nNP[[i]], {i, trialDeg}]/totAB]
CHSH = Abs[N[mean[[315]]] - N[mean[[225]]] + N[mean[[405]]] + N[mean[[45]]]]

```

```
AveA = 0.00271
AveB = 0.00062
P(A+) = 0.501355
P(B+) = 0.50031
```

```
Out[715]= 200 000
```

```
Out[716]= 0.250695
```

```
Out[717]= 0.24903
```

```
Out[718]= 0.25066
```

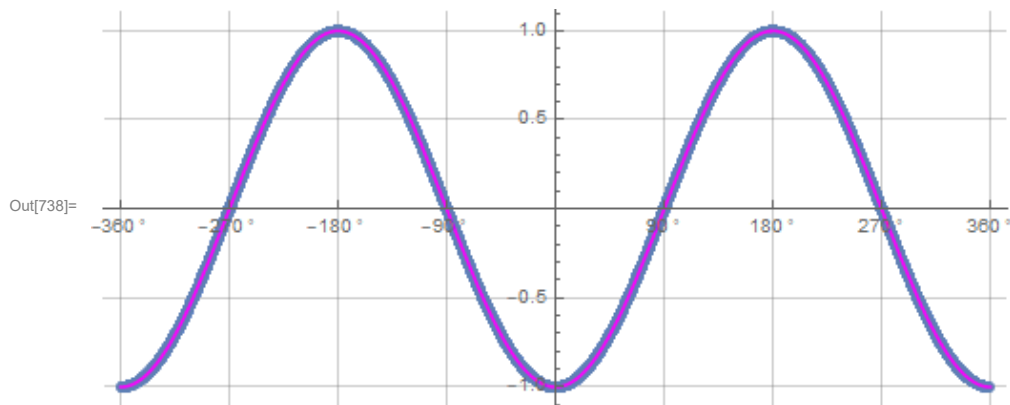
```
Out[719]= 0.249615
```

```
Out[720]= 2.71645
```

Product Calculation

```
q = 0;
q2a = outA[ [All, 6] ];
q2b = outB[ [All, 6] ];
plotq = Table[ {0, 0}, m];
angle = ConstantArray[0, m];
Do[ If[  $\lambda_2$ [ [i] ] == 1, q = q2a[ [i] ] ** q2b[ [i] ], q = q2b[ [i] ] ** q2a[ [i] ] ];
  angle = theta[ [i] ] - 361;
  plotq[ [i] ] = {angle, Re[q]}, {i, m}
sim = ListPlot[ plotq, PlotMarkers -> {Automatic, Small}, AspectRatio -> 7/16,
  Ticks -> { { -360, -360 ° }, { -270, -270 ° }, { -180, -180 ° }, { -90, -90 ° }, { 0, 0 ° }, { 90, 90 ° },
    { 180, 180 ° }, { 270, 270 ° }, { 360, 360 ° } }, Automatic], GridLines -> Automatic];
negcos1 = Plot[ -Cos[x Degree], {x, -360, 360}, PlotStyle -> {Magenta}];
Show[sim, negcos1]
```

```
In[738]= Import["prodcalc200k.png"]
```



Blue is the correlation data and magenta is the -cosine curve for an exact match.

```
(*dev1=ConstantArray[2,720];  
dev2=ConstantArray[2,720];  
dev3=ConstantArray[2,720];  
Do[dev1=mean[[i]];dev2[[i]]={dev1,i},{i,720}]  
  devang=dev2[[All,2]]-361;  
Do[dev3[[i]]=mean[[i]]+Cos[devang[[i]] Degree],{i,720}]  
ListPlot[N[dev3],PlotMarkers->{Automatic,Tiny},Joined→True,AspectRatio→1/2,  
  Ticks→{{{0,-360°},{90,-270°},{180,-180°},{270,-90°},{360,0°},{450,90°},  
    {540,180°},{630,270°},{720,360°}},Automatic},GridLines→Automatic]*)
```