

Simulation Based on Michel Fodje's epr-simple simulation translated from Python to Mathematica by John Reed 13 Nov 2013 and Quaternions Modified by Fred Diether for Completely Local-Realistic Sep 2021 Some parts by Bill Nelson. Includes Joy's S^3 Quaternion Model.

Load Quaternion Package, Set Run Time Parameters, Initialize Arrays and Tables

```
In[2367]:= << Quaternions` ;
 $\beta_0$  = Quaternion[1, 0, 0, 0];
 $\beta_1$  = Quaternion[0, 1, 0, 0];
 $\beta_2$  = Quaternion[0, 0, 1, 0];
 $\beta_3$  = Quaternion[0, 0, 0, 1];
Qcoordinates = { $\beta_1$ ,  $\beta_2$ ,  $\beta_3$ };
m = 1000000;
trialDeg = 721;
Ls1 = ConstantArray[0, m];
Ls2 = ConstantArray[0, m];
 $\lambda_1$  = ConstantArray[0, m];
 $\lambda_2$  = ConstantArray[0, m];
qa = ConstantArray[0, m];
aq = ConstantArray[0, m];
aq1 = ConstantArray[0, m];
qa1 = ConstantArray[0, m];
qb = ConstantArray[0, m];
aq = ConstantArray[0, m];
bq1 = ConstantArray[0, m];
qb1 = ConstantArray[0, m];
aa1 = ConstantArray[0, m];
bb1 = ConstantArray[0, m];
outA1 = Table[{0, 0, 0, 0}, m];
outA2 = Table[{0, 0, 0, 0}, m];
outB1 = Table[{0, 0, 0, 0}, m];
outB2 = Table[{0, 0, 0, 0}, m];
plotq = Table[{0, 0}, m];
a1 = ConstantArray[0, m];
b1 = ConstantArray[0, m];
A = ConstantArray[0, m];
B = ConstantArray[0, m];
nPP = ConstantArray[0, trialDeg];
nNN = ConstantArray[0, trialDeg];
nPN = ConstantArray[0, trialDeg];
nNP = ConstantArray[0, trialDeg];
nAP = ConstantArray[0, trialDeg];
nBP = ConstantArray[0, trialDeg];
nAN = ConstantArray[0, trialDeg];
nBN = ConstantArray[0, trialDeg];
 $\phi$  = 3;  $\beta$  = 0.3;  $\xi$  = 0.921; (*Adustable parameters for fine tuning*)
```

Generating Particle Data with Three Independent Do-Loops

```

In[2407]:= Do[ $\theta = \text{RandomReal}[\{-179, 180\}];$  (*Singlet vector angle*) (*Hidden Variable*)
   $\lambda 1[[i]] = \beta \left( \text{Cos}\left[\frac{\theta}{3}\right]^2\right);$ 
   $\lambda 2[[i]] = \xi \left( \text{Cos}\left[\frac{\theta}{3}\right]^2\right);$ 
   $\theta\theta = \text{N}[\text{Flatten}[\{\text{FromPolarCoordinates}[\{1, \theta * \pi/180\}], \theta\}]];
  \text{Ls1}[[i]] = \theta\theta.\text{Qcoordinates};
  \text{Ls2}[[i]] = -\theta\theta.\text{Qcoordinates}, \{i, m\}]

In[2408]:= Do[ $a = \text{RandomInteger}[\{-179, 180\}];$  (*Detector vector angle 1 degree increments*)
   $aa1[[i]] = a;$ 
   $aa = \text{N}[\text{Flatten}[\{\text{FromPolarCoordinates}[\{1, a * \pi/180\}], \theta\}]];
  \text{Da} = aa.\text{Qcoordinates};$  (*Convert to quaternion coordinates*)
   $qa = \text{Da} ** \text{Ls1}[[i]];$ 
   $qa1[[i]] = qa;$ 
   $aq = -(-\text{Da} ** \text{Ls1}[[i]]);$ 
   $aq1[[i]] = aq;$ 
   $\text{If}[\text{Abs}[\text{Re}[qa]] > \lambda 1[[i]], \text{Aa1} = \text{Sign}[\text{Re}[qa]], \text{Aa1} = \{\}];$ 
   $\text{outA1}[[i]] = \{a, \text{Aa1}, i, qa\}, \{i, m\}]
  \text{Do}[\text{If}[\text{Abs}[\text{Re}[aq1[[i]]]] < \lambda 2[[i]], \text{Aa2} = -\text{Sign}[aq1[[i]][[4]]], \text{Aa2} = \{\}];$ 
   $\text{outA2}[[i]] = \{aa1[[i]], \text{Aa2}, i + m, qa1[[i]]\}, \{i, m\}]
  \text{outA} = \text{Catenate}[\{\text{outA1}, \text{outA2}\}];
  \text{Length}[\text{outA2}]

Out[2411]= 1000000

In[2412]:= Do[ $b = \text{RandomInteger}[\{-179, 180\}];$  (*Detector vector angle 1 degree increments*)
   $bb1[[i]] = b;$ 
   $bb = \text{N}[\text{Flatten}[\{\text{FromPolarCoordinates}[\{1, b * \pi/180\}], \theta\}]];
  \text{Db} = bb.\text{Qcoordinates};$  (*Convert to quaternion coordinates*)
   $qb = \text{Ls2}[[i]] ** \text{Db};$ 
   $qb1[[i]] = qb;$ 
   $bq = -(-\text{Ls2}[[i]] ** \text{Db});$ 
   $bq1[[i]] = bq;$ 
   $\text{If}[\text{Abs}[\text{Re}[qb]] > \lambda 1[[i]], \text{Bb1} = \text{Sign}[\text{Re}[qb]], \text{Bb1} = \{\}];$ 
   $\text{outB1}[[i]] = \{b, \text{Bb1}, i, qb\}, \{i, m\}]
  \text{Do}[\text{If}[\text{Abs}[\text{Re}[bq1[[i]]]] < \lambda 2[[i]], \text{Bb2} = \text{Sign}[bq1[[i]][[4]]], \text{Bb2} = \{\}];$ 
   $\text{outB2}[[i]] = \{bb1[[i]], \text{Bb2}, i + m, qb1[[i]]\}, \{i, m\}]
  \text{outB} = \text{Catenate}[\{\text{outB1}, \text{outB2}\}];
  \text{Length}[\text{outB2}]

Out[2415]= 1000000$$$ 
```

Statistical Analysis of the Particle Data Received from Alice and Bob


```
In[2416]:= m2 = 2 * m;
theta = ConstantArray[0, m2];
a1 = outA[[All, 1]]; A = outA[[All, 2]]; b1 = outB[[All, 1]]; B = outB[[All, 2]];
Do[th = a1[[i]] - b1[[i]] + 361;
  (*All angles are shifted by 361 degrees since 01 is an index*)
  theta[[i]] = th;
  aliced = A[[i]]; bobD = B[[i]];
  If[aliceD == 1, nAP[[th]]++];
  If[bobD == 1, nBP[[th]]++];
  If[aliceD == -1, nAN[[th]]++];
  If[bobD == -1, nBN[[th]]++];
  If[aliceD == 1 && bobD == 1, nPP[[th]]++];
  If[aliceD == 1 && bobD == -1, nPN[[th]]++];
  If[aliceD == -1 && bobD == 1, nNP[[th]]++];
  If[aliceD == -1 && bobD == -1, nNN[[th]]++], {i, m2}]
```

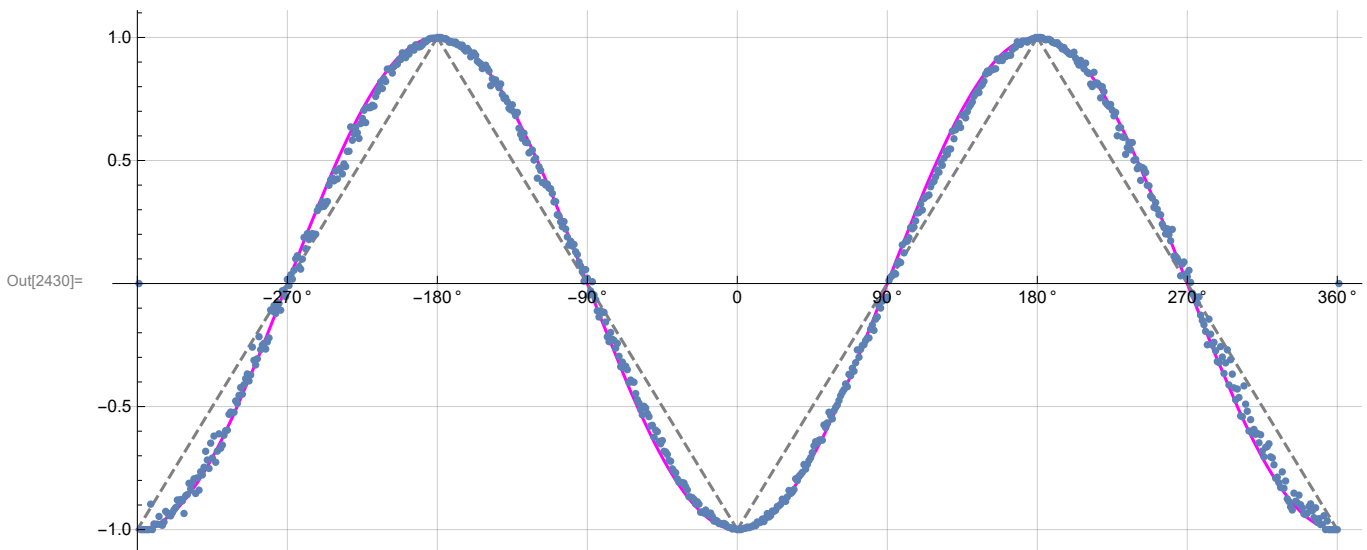
Calculating Mean Values of A, B, and AB, and Plotting the Results

```
In[2420]:= mean = ConstantArray[0, trialDeg];
sum1 = ConstantArray[0, trialDeg];
sum2 = ConstantArray[0, trialDeg];
Do[sum1[[i]] = (nPP[[i]] + nNN[[i]] - nPN[[i]] - nNP[[i]]);
  sum2[[i]] = nPP[[i]] + nPN[[i]] + nNP[[i]] + nNN[[i]] + 0.0000001;
  mean[[i]] = sum1[[i]] / sum2[[i]], {i, trialDeg}]

In[2424]:= simulation = ListPlot[mean, PlotMarkers -> {Automatic, Tiny}];
negcos = Plot[-Cos[x Degree], {x, 0, 720}, PlotStyle -> {Magenta}, AspectRatio -> 7 / 16,
  Ticks -> {{0, -360}, {90, -270}, {180, -180}, {270, -90}, {360, 0}, {450, 90},
    {540, 180}, {630, 270}, {720, 360}}, Automatic, GridLines -> Automatic];
p1 = Plot[-1 + 2 x Degree / π, {x, 0, 180}, PlotStyle -> {Gray, Dashed}];
p2 = Plot[3 - 2 x Degree / π, {x, 180, 360}, PlotStyle -> {Gray, Dashed}];
p3 = Plot[-5 + 2 x Degree / π, {x, 360, 540}, PlotStyle -> {Gray, Dashed}];
p4 = Plot[7 - 2 x Degree / π, {x, 540, 720}, PlotStyle -> {Gray, Dashed}];
```

Comparing Mean Values with -Cosine Function and Computing Averages

```
In[2430]:= Show[negcos, p1, p2, p3, p4, simulation]
```



In[2431]:=

```

A1 = DeleteCases[A, {}];
m3 = Length[A1];
B1 = DeleteCases[B, {}];
m4 = Length[B1];
AveA = N[Sum[A1[[i]], {i, m3}]/m3];
AveB = N[Sum[B1[[i]], {i, m4}]/m4];
Print["AveA = ", AveA];
Print["AveB = ", AveB];
PAP = N[Sum[nAP[[i]], {i, trialDeg}]];
PBP = N[Sum[nBP[[i]], {i, trialDeg}]];
PAN = N[Sum[nAN[[i]], {i, trialDeg}]];
PBN = N[Sum[nBN[[i]], {i, trialDeg}]];
PA1 = PAP / (PAP + PAN);
PB1 = PBP / (PBP + PBN);
Print["P(A+) = ", PA1]
Print["P(B+) = ", PB1]
totAB = Sum[nPP[[i]] + nNN[[i]] + nPN[[i]] + nNP[[i]], {i, trialDeg}];
Print["Total Events = ", totAB]
PP = N[Sum[nPP[[i]], {i, trialDeg}]/totAB];
NN = N[Sum[nNN[[i]], {i, trialDeg}]/totAB];
PN = N[Sum[nPN[[i]], {i, trialDeg}]/totAB];
NP = N[Sum[nNP[[i]], {i, trialDeg}]/totAB];
Print["Ave ++ = ", PP]
Print["Ave -- = ", NN]
Print["Ave +- = ", PN]
Print["Ave -+ = ", NP]
CHSH = Abs[N[mean[[315]]] - N[mean[[225]]] + N[mean[[405]]] + N[mean[[45]]]];
Print["Approx. CHSH = ", CHSH]

AveA = 0.000721889
AveB = -0.000484366
P(A+) = 0.500361
P(B+) = 0.499758
Total Events = 998767
Ave ++ = 0.249562
Ave -- = 0.249807
Ave +- = 0.250687
Ave -+ = 0.249944
Approx. CHSH = 2.76107

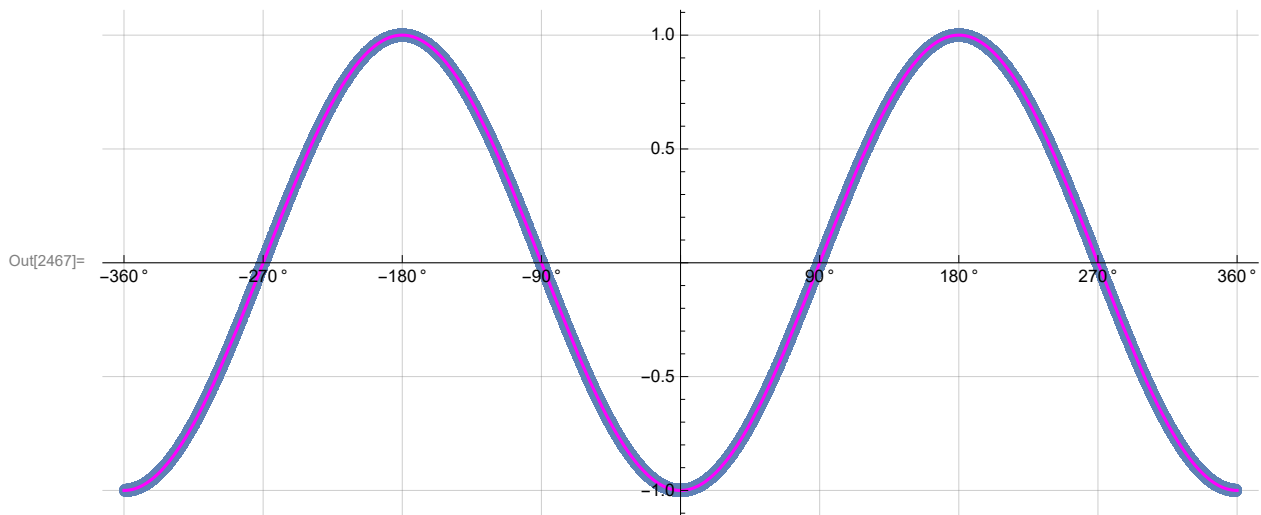
```

Product Calculation

```

In[2459]:= q = 0;
q2a = outA[[All, 4]];
q2b = outB[[All, 4]];
plotq = Table[{0, 0}, m];
angle = ConstantArray[0, m];
Do[If[λ2[[i]] == 1, q = q2a[[i]] ** q2b[[i]], q = q2b[[i]] ** q2a[[i]]];
  angle = theta[[i]] - 361;
  plotq[[i]] = {angle, Re[q]}, {i, m}]
sim = ListPlot[plotq, PlotMarkers → {Automatic, Small}, AspectRatio → 7/16,
  Ticks → {{{-360, -360 °}, {-270, -270 °}, {-180, -180 °}, {-90, -90 °}, {0, 0 °}, {90, 90 °},
    {180, 180 °}, {270, 270 °}, {360, 360 °}}, Automatic], GridLines → Automatic];
negcos1 = Plot[-Cos[x Degree], {x, -360, 360}, PlotStyle → {Magenta}];
Show[sim, negcos1]

```

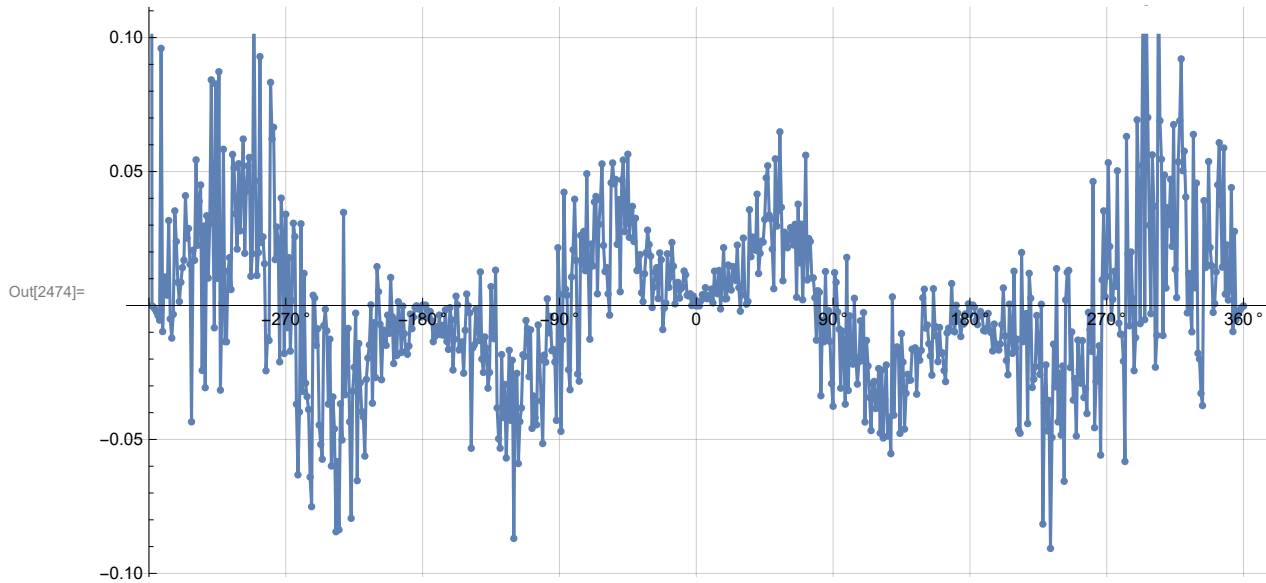


Blue is the correlation data and magenta is the $-\cos$ curve for an exact match.

```

In[2468]:= dev1 = ConstantArray[2, 720];
dev2 = ConstantArray[2, 720];
dev3 = ConstantArray[2, 720];
Do[dev1 = mean[[i]]; dev2[[i]] = {dev1, i}, {i, 720}]
devang = dev2[[All, 2]] - 361;
Do[dev3[[i]] = mean[[i]] + Cos[devang[[i]] Degree], {i, 720}]
ListPlot[N[dev3], PlotMarkers -> {Automatic, Tiny}, Joined -> True, AspectRatio -> 1/2,
  Ticks -> {{0, -360 °}, {90, -270 °}, {180, -180 °}, {270, -90 °}, {360, 0 °}, {450, 90 °},
    {540, 180 °}, {630, 270 °}, {720, 360 °}}, Automatic], GridLines -> Automatic]

```



```

In[2475]:= N[Mean[Abs[dev3]]]
N[Mean[dev3]]

```

Out[2475]= 0.0241046

Out[2476]= 0.00156817